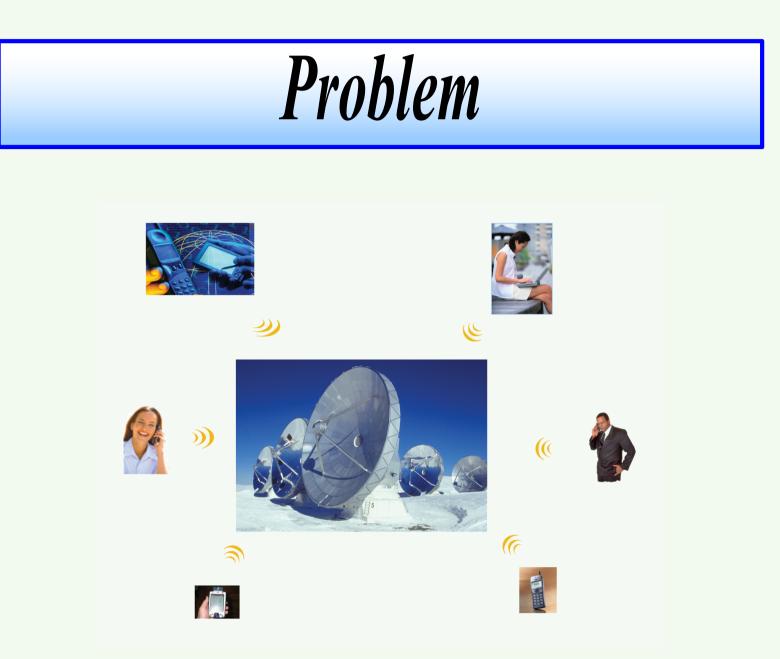


# Blind source separation of convolutive mixtures



### **Problem statement:**

A mixture of K statistically independent sources is observed by using N sensors,  $N \ge K$ .

### **Assumption on the mixture:**

*Linear filtering relation (but unknown) between* the sources and the observations.

### **Goal:**

We want to reconstruct the sources.

### **Possible applications:**

- Monitoring of radio-electrical spectrum
- Multi-speaker sound recording
- Biomedical signal processing, ...



**Proposed** approach

#### **Notations:**

-  $\{s_k(t)\}, k \in [1, ..., K]$  the K sources. -  $\{y_n(t)\}, n \in [1, ..., N]$  the N observations. - Model:

$$\forall n \in [1, ..., N],$$

$$y_{n}(t) = \sum_{k=1}^{K} [(H_{n,k} * s_{k}) (t)]$$

#### **Deflation approach:**

Determine a filter with N inputs and 1 output  $g=(g_1,\ldots,g_N)$  such that:

$$r_{g}(t) = \sum_{n=1}^{N} [(g_{n} * y_{n}) (t)]$$

corresponds to one of the source signals. We subtract then the contribution of the extracted source from each sensor and we iterate the process.

### **Determination of the filter g:**

Construction of contrast functions  $J(r_g)$  depending on the statistics of signal  $r_{g}$  having a global maximum when the sources are separated. *For example:* 

$$J(r_g) = \begin{vmatrix} \mathbf{E}(|r_g(t)|^4) \\ \frac{1}{(\mathbf{E}(|r_g(t)|^2))^2} - 2 \end{vmatrix}$$

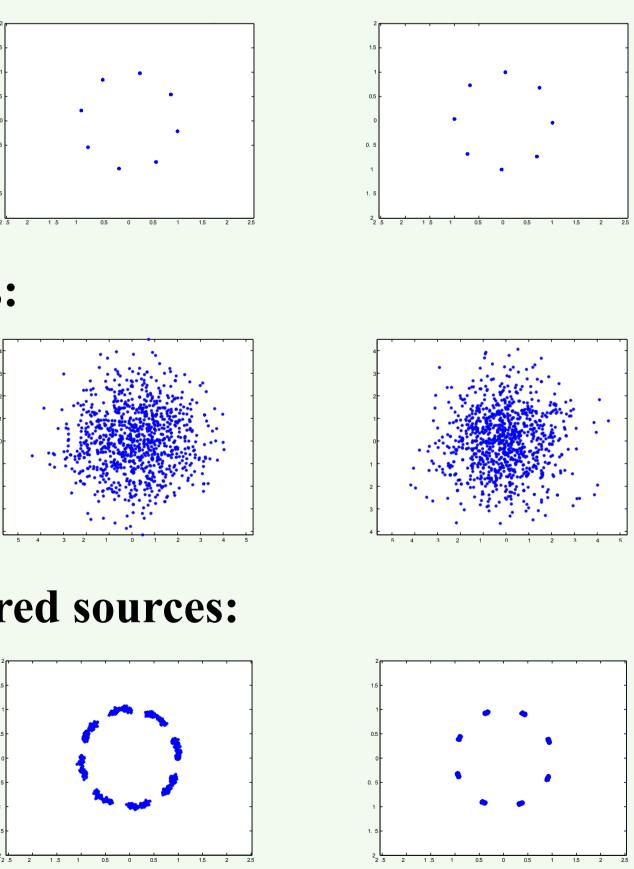
*if the source signals are stationary.* 

# Some illustrations

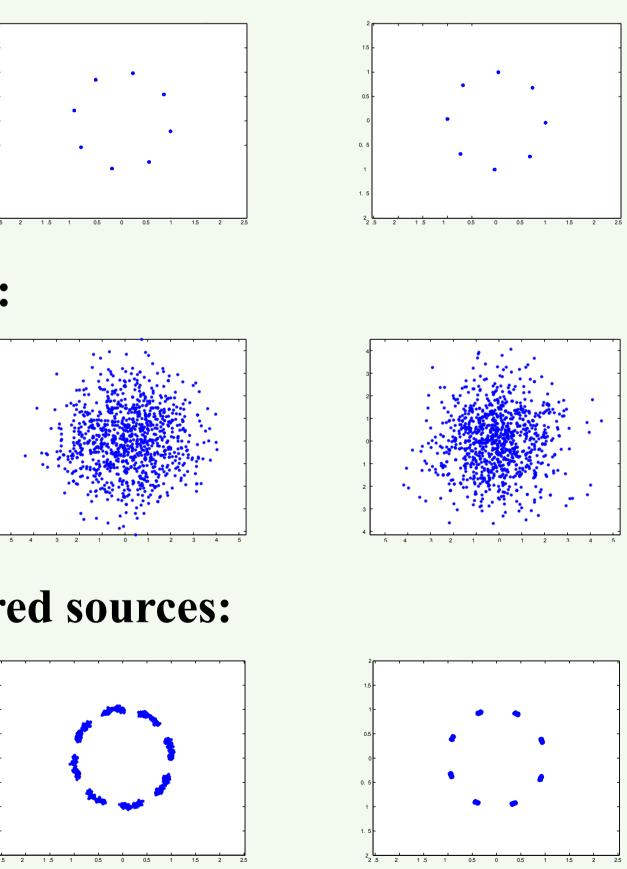
## **Context:**

### Sources: signals with modulus 1.

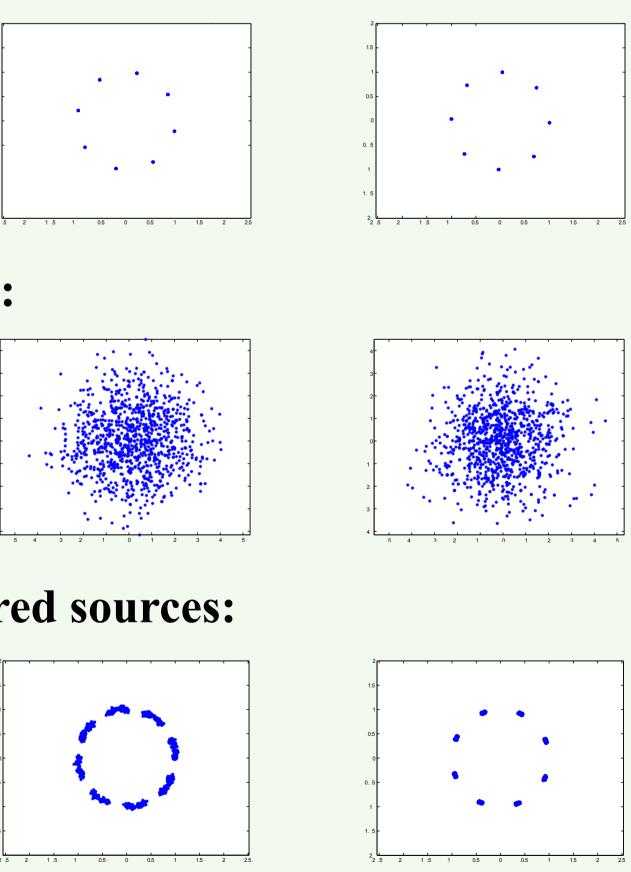
### **True sources:**



### Sensors:



### **Recovered sources:**



### Contact: Antoine Chevreuil, Elena Florian, Philippe Loubaton

*3 sources and 4 sensors, 3-path channel with fading.* 

CPM (continuous phase modulation) communication